

ECE 161C: Introduction to Image Processing

Morphological Processing

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Outline

- Morphology: Introduction
- Basic Definitions
- Erosion and Dilation
- Opening and Closing
- Graylevel Morphology
- Morphological Filtering

Morphology: Introduction

What does morphology even mean?

The study of shape and structure

- Language: Set Theory

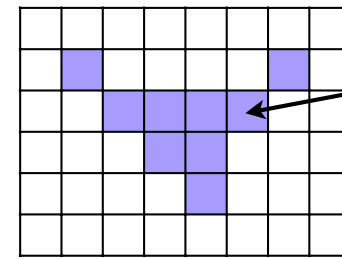
- Binary images (bitmap)

$\implies$ Sets of points in 2D space ($\mathbb{Z}^2$)

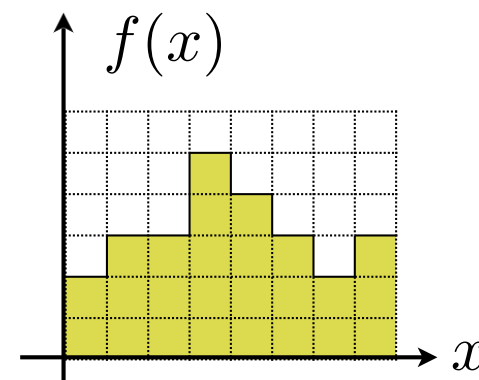
- Quantized graylevel images

$\implies$ Sets of points in 3D space ($\mathbb{Z}^3$)

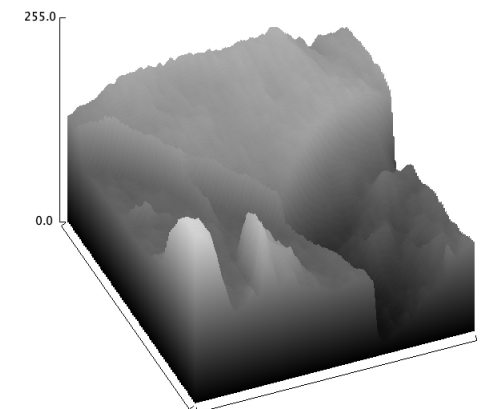
$$(x, y, Q(f(x, y))) \in \mathbb{Z}^3$$



A
object vs. background



1D signal



2D image

- Types of transformations

- Set-theoretic: Union, intersection, etc.
- With a structuring element: dilation, erosion

Morphology: Application Areas

Classification of objects or image features based on shape

- Examples
 - Extraction of objects with a specific shape
 - Extraction with a size smaller or greater than a limit
 - Contour detection
- Typical stages in an image-processing pipeline where it is useful
 - Preprocessing: noise reduction, simplification
 - Feature detection
 - Segmentation: Contour extraction
 - Postprocessing: shape cleaning and simplification
- Main application areas
 - Material sciences, mineralogy, granulometry
 - Medicine and biology: Cell counting, cytology, gel electrophoresis, microarrays
 - Robotics and machine vision

Basic Definitions

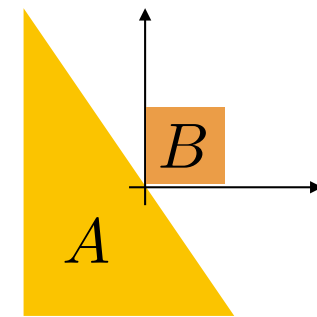
- “Universe” set

$\mathbb{E}$ is the set of every possible element (e.g., $\mathbb{E} = \mathbb{Z}^2$ or $\mathbb{E} = \mathbb{Z}^3$ or $\mathbb{E} = \mathbb{R}^2$)

- Sets and subsets

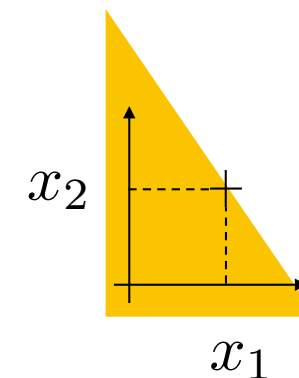
$$A, B \subset \mathbb{E}$$

Elements: $a = (a_1, a_2) \in A$, $b = (b_1, b_2) \in B$



- Translation by $x = (x_1, x_2)$

$$(A)_x = \{c : c = a + x, a \in A\}$$



Basic Definitions (cont'd)

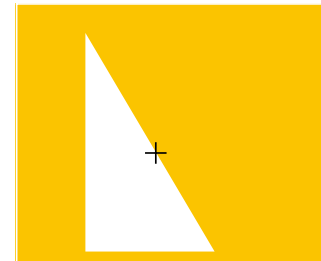
- Reflection or symmetry

$$A^s = \{x \in \mathbb{E} : x = -a, a \in A\}$$



- Complement

$$A^c = \{x \in \mathbb{E} : x \in \mathbb{E} \setminus A\}$$



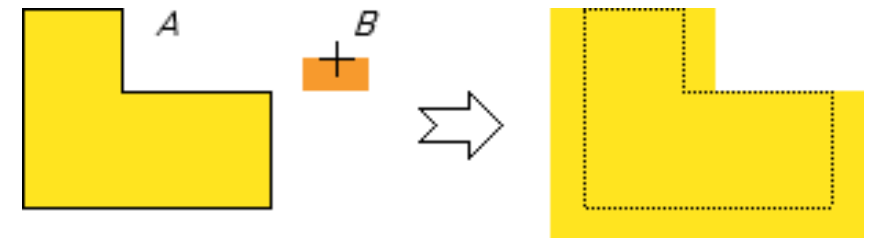
Dilation and Erosion in $\mathbb{R}^2$

- Structuring element



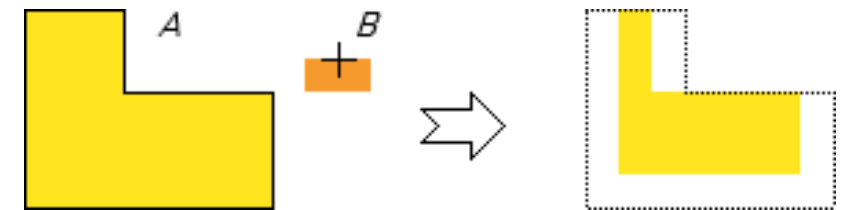
- Dilation

$$A \oplus B = \{x \in \mathbb{E} : (B^s)_x \cap A \neq \emptyset\} = \bigcup_{x \in A} (B)_x$$

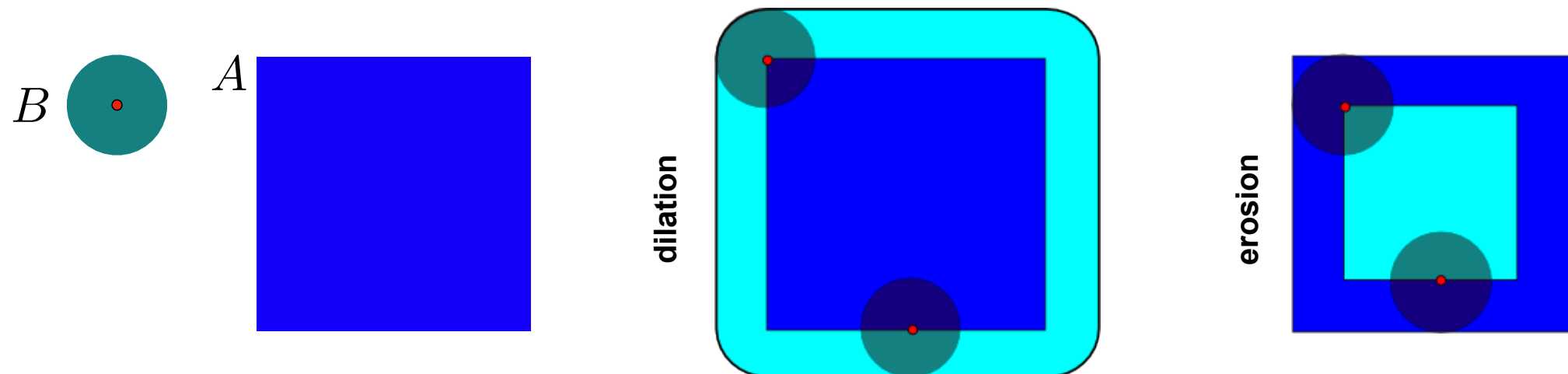


- Erosion

$$A \ominus B = \{x \in \mathbb{E} : (B)_x \subset A\} = \bigcap_{x \in B^s} (A)_x$$



- Example



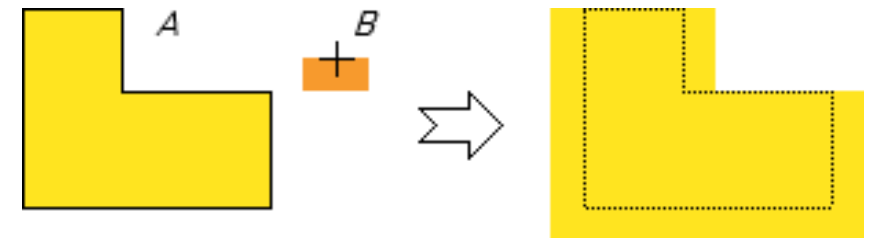
Dilation and Erosion in $\mathbb{R}^2$

- Structuring element



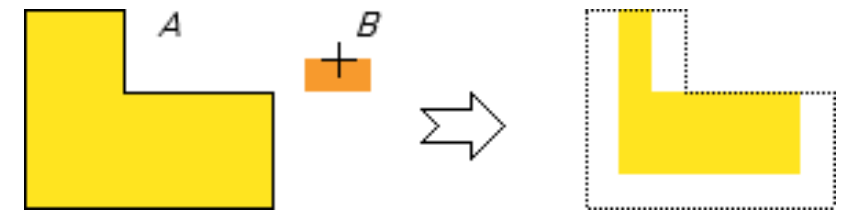
- Dilation

$$A \oplus B = \{x \in \mathbb{E} : (B^s)_x \cap A \neq \emptyset\} = \bigcup_{x \in A} (B)_x$$



- Erosion

$$A \ominus B = \{x \in \mathbb{E} : (B)_x \subset A\} = \bigcap_{x \in B^s} (A)_x$$



- Duality relations

$$A \ominus B = (A^c \oplus B^s)^c$$

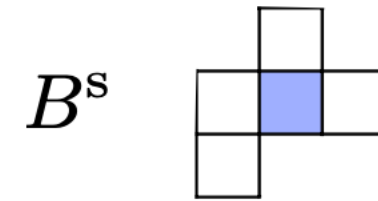
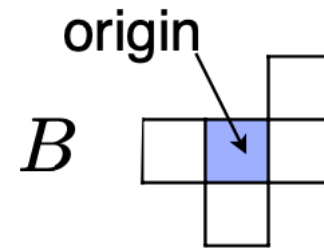
“Erosion = Dilation of complement”

$$A \oplus B = (A^c \ominus B^s)^c$$

“Dilation = Erosion of complement”

Dilation and Erosion in $\mathbb{Z}^2$

- Structuring element



- Dilation

$$A \oplus B = \{x \in \mathbb{E} : (B^s)_x \cap A \neq \emptyset\} = \bigcup_{x \in A} (B)_x$$

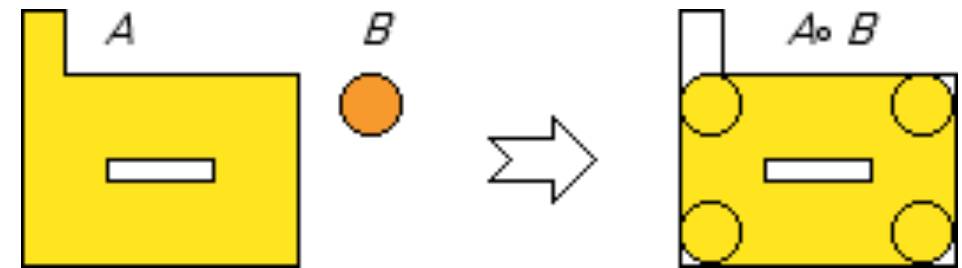
- Erosion

$$A \ominus B = \{x \in \mathbb{E} : (B)_x \subset A\} = \bigcap_{x \in B^s} (A)_x$$

Opening

- Opening operator

$$A \circ B = (A \ominus B) \oplus B$$

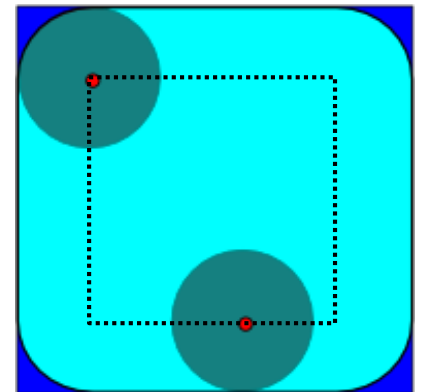


- Interpretation 1: “Smallest” set that contains a given erosion $A \ominus B$
- Interpretation 2: Union of all shifted B 's included in A

$$A \circ B = \bigcup_{x \in \mathbb{E}} \{(B)_x : (B)_x \subset A\}$$

- Properties

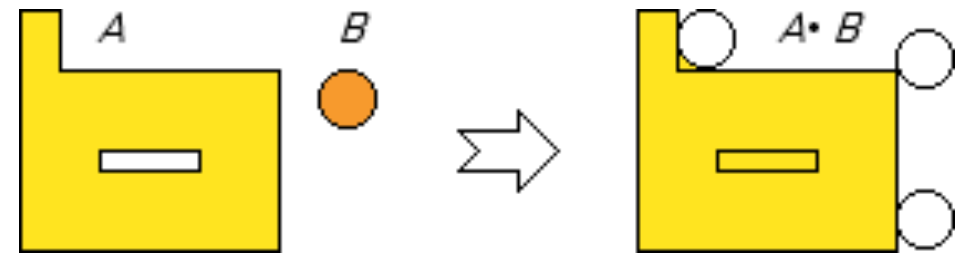
- Subset $A \circ B \subset A$
- Invariance to origin $A \circ (B)_x = A \circ B$ for all $x \in \mathbb{E}$
- Idempotence $(A \circ B) \circ B = A \circ B$
- Order preservation $C \subset D \Rightarrow (C \circ B) \subset (D \circ B)$



Closing

- Closing operator

$$A \bullet B = (A \oplus B) \ominus B$$

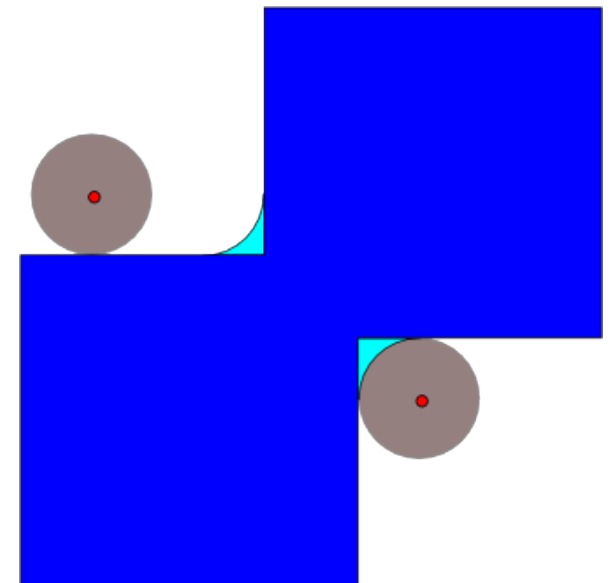


- Interpretation 1: “Largest” set that contains a given dilation $A \oplus B$
- Interpretation 2: Complement of all shifted B^s 's included in A^c

$$A \bullet B = \left(\bigcup_{x \in \mathbb{E}} \{(B^s)_x : (B^s)_x \subset A^c\} \right)^c$$

- Properties

- Superset $A \bullet B \supset A$
- Invariance to origin $A \bullet (B)_x = A \bullet B$ for all $x \in \mathbb{E}$
- Idempotence $(A \bullet B) \bullet B = A \bullet B$
- Order preservation $C \subset D \Rightarrow (C \bullet B) \subset (D \bullet B)$



Duality Relations

- Erosion and dilation

$$A \ominus B = (A^c \oplus B^s)^c$$

$$A \oplus B = (A^c \ominus B^s)^c$$

- Opening and closing

$$A \circ B = (A^c \bullet B^s)^c$$

$$A \bullet B = (A^c \circ B^s)^c$$

Distance Map and Watershed

$$A_0[\mathbf{k}] = \begin{cases} 1, & \mathbf{k} \in \text{object} \\ 0, & \mathbf{k} \in \text{background} \end{cases}$$

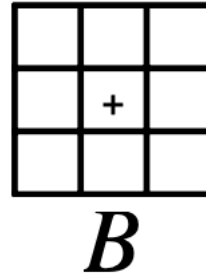
$n = 0$

while $\max(A_n) = 1$ **do**

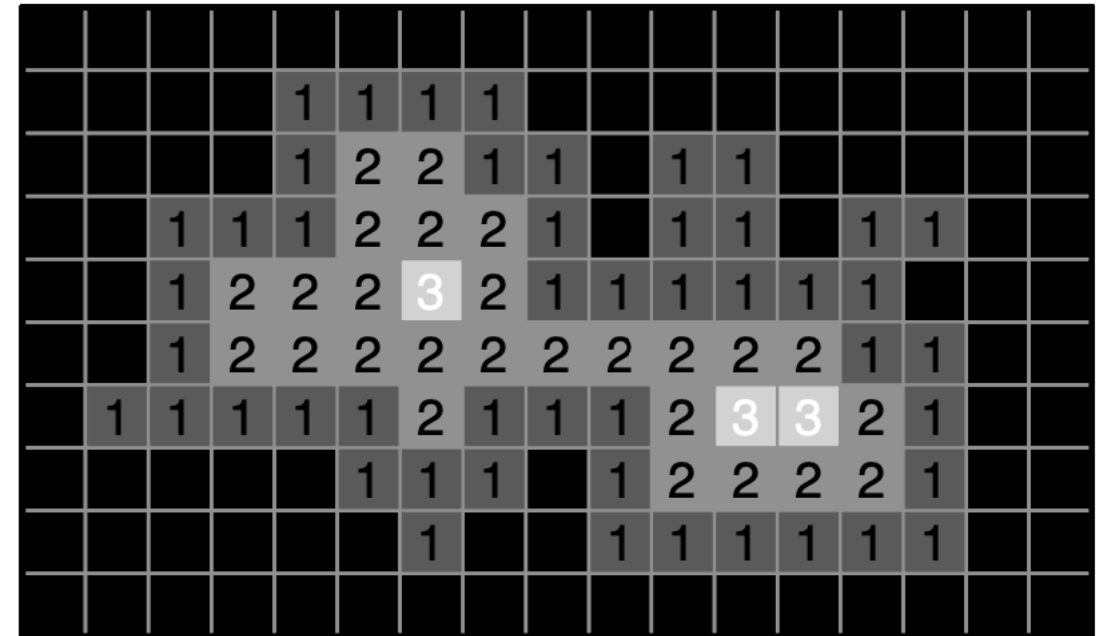
$A_{n+1} = \text{erode}(A_n, B)$

$D_{\text{map}} = D_{\text{map}} + (n + 1)(A_n - A_{n+1})$

$n = n + 1$

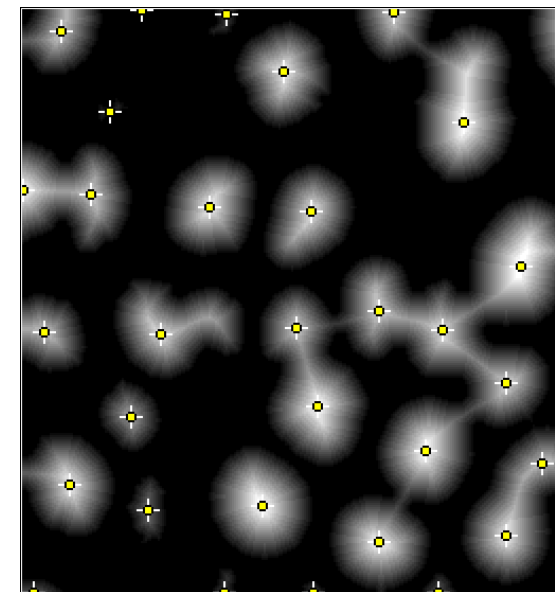
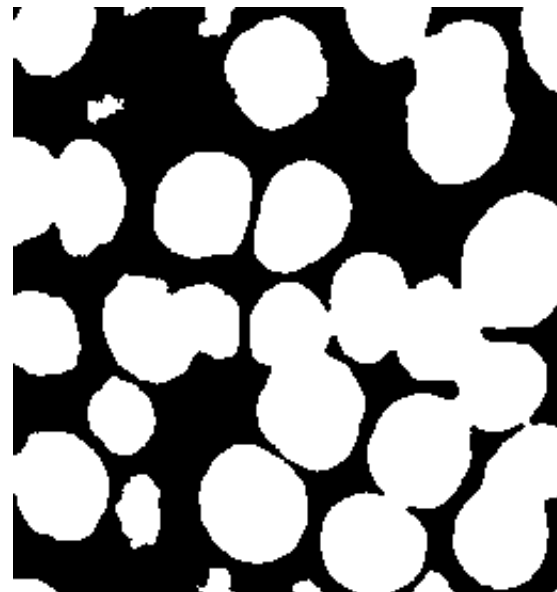
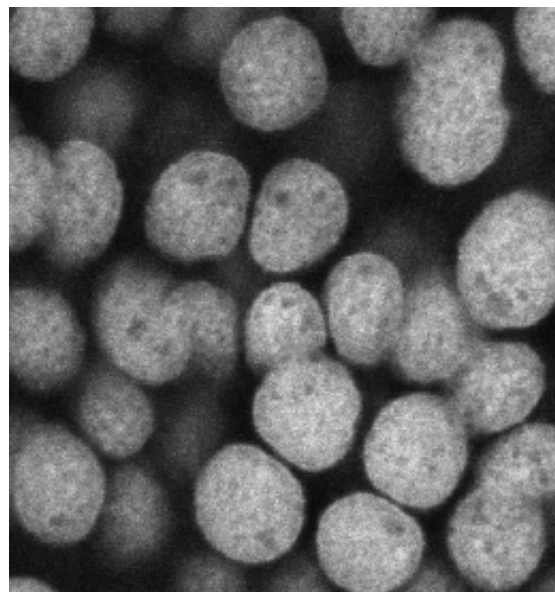


☐ object
☒ background



original image

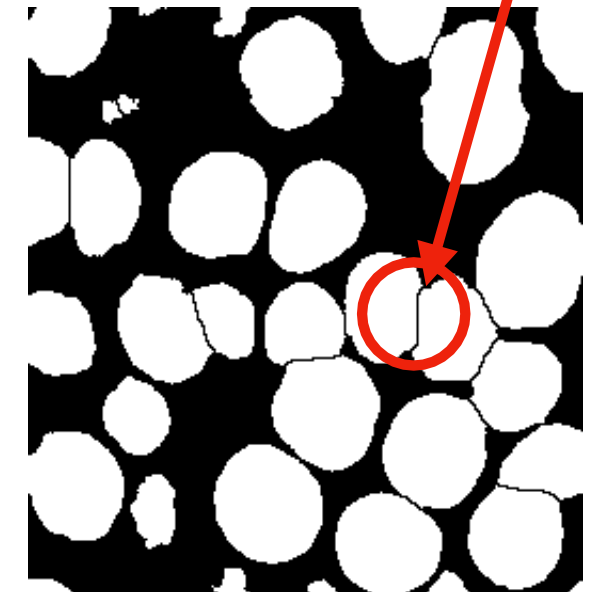
thresholded image



local maxima

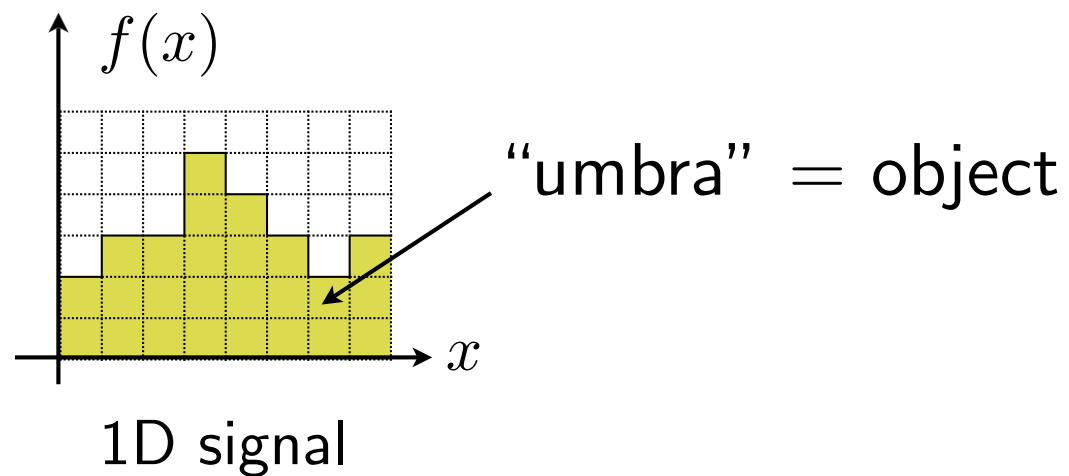


seeds of watersheds



<https://bigwww.epfl.ch/demo/ip/demos/watershed/>

Graylevel Morphology



Structuring elements are now **sequences**, e.g., $b[\mathbf{k}] = b[k_1, k_2]$

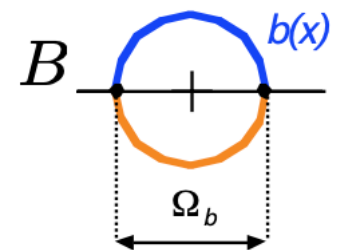
- Common structural elements are **symmetric**

- Horizontal: W -neighborhood

- Volumetric: approximation of a ball (rolling ball)

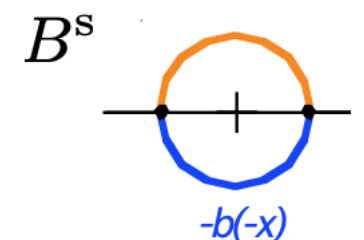
- Dilation

$$(f \oplus b)[\mathbf{k}] = \max_{\mathbf{k}_0 \in \Omega_b} \{f[\mathbf{k} - \mathbf{k}_0] + b[\mathbf{k}_0] : (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$$



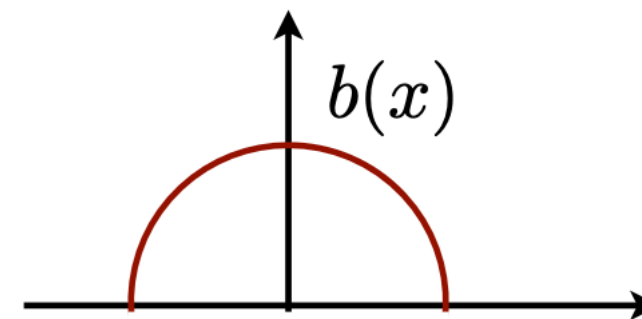
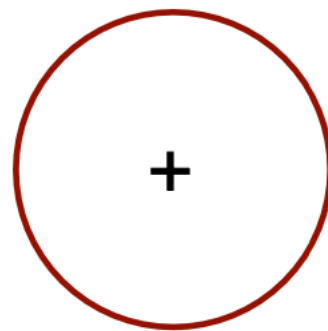
- Erosion

$$(f \ominus b)[\mathbf{k}] = \min_{-\mathbf{k}_0 \in \Omega_b} \{f[\mathbf{k} - \mathbf{k}_0] - b[-\mathbf{k}_0] : (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$$



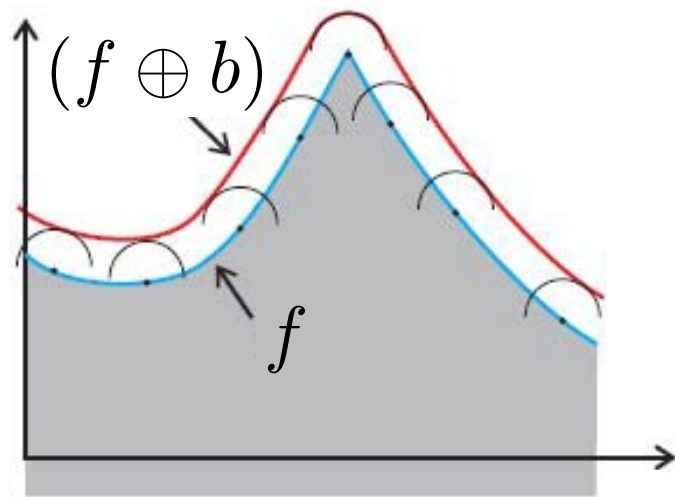
Graylevel Dilation and Erosion

Structuring element:



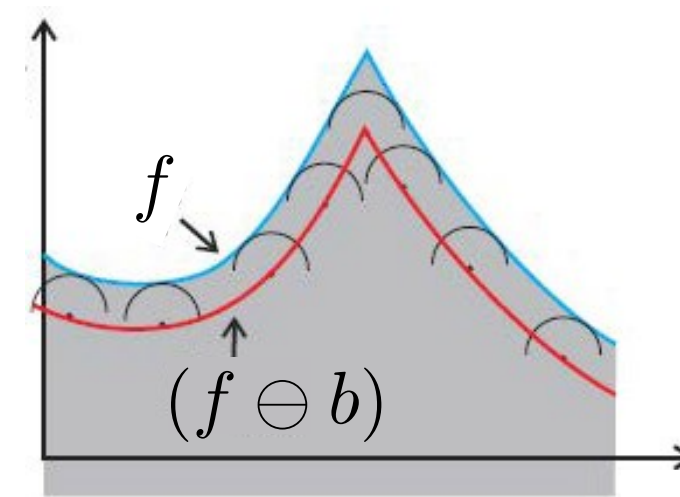
Reminder:

$$A \oplus B = \bigcup_{x \in A} (B)_x$$



$$\max_{\mathbf{k}_0 \in \Omega_b} \{f[\mathbf{k} - \mathbf{k}_0] + b[\mathbf{k}_0] : (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$$

$$A \ominus B = \{x \in \mathbb{E} : (B)_x \subset A\}$$



$$\min_{-\mathbf{k}_0 \in \Omega_b} \{f[\mathbf{k} - \mathbf{k}_0] - b[-\mathbf{k}_0] : (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$$

Graylevel Dilation and Erosion

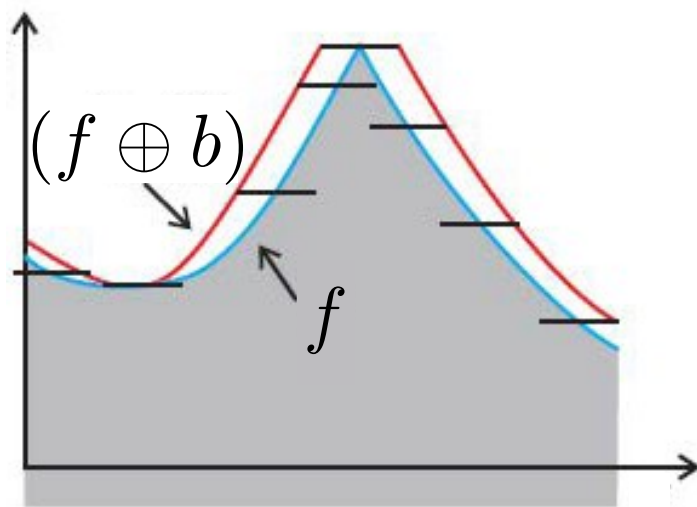
Structuring element:

$$b(x) = 0$$

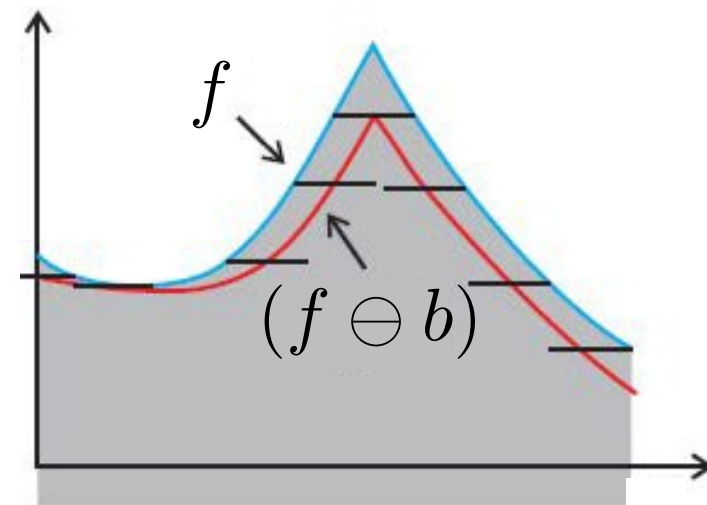

$$\Omega_b = W$$

Reminder:

$$A \oplus B = \bigcup_{x \in A} (B)_x$$



$$A \ominus B = \{x \in \mathbb{E} : (B)_x \subset A\}$$



$$\max_{\mathbf{k}_0 \in \Omega_b} \{f[\mathbf{k} - \mathbf{k}_0] + b[\mathbf{k}_0] : (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$$

$$= \max_{\mathbf{k}_0 \in W} \{f[\mathbf{k} - \mathbf{k}_0] : (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$$

max-filter

$$\min_{-\mathbf{k}_0 \in \Omega_b} \{f[\mathbf{k} - \mathbf{k}_0] - b[-\mathbf{k}_0] : (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$$

$$= \min_{-\mathbf{k}_0 \in W} \{f[\mathbf{k} - \mathbf{k}_0] : (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$$

min-filter

Morphological Filtering in Practice

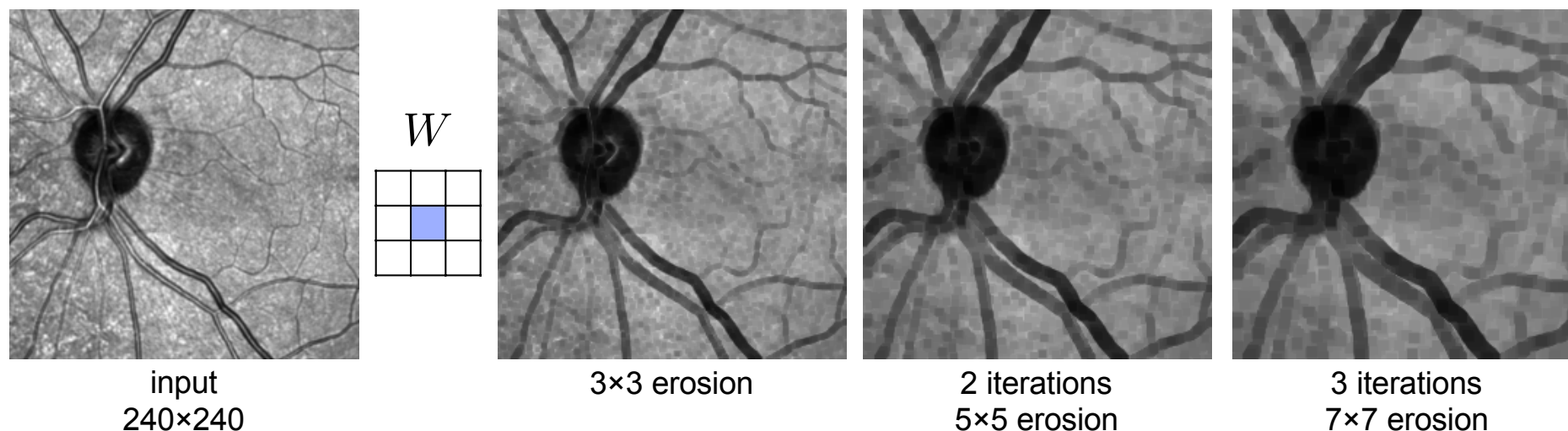
- Special case: $b[\mathbf{y}] = 0$ and $\Omega_b = W$

Dilation = Max-filter: $\max_{\mathbf{k}_0 \in W} \{f[\mathbf{k} - \mathbf{k}_0] : (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$

Erosion = Min-filter: $\min_{\mathbf{k}_0 \in W} \{f[\mathbf{k} - \mathbf{k}_0] : (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$

- Benefit of iteration

Dilation/erosion can be iterated to construct larger equivalent structuring elements

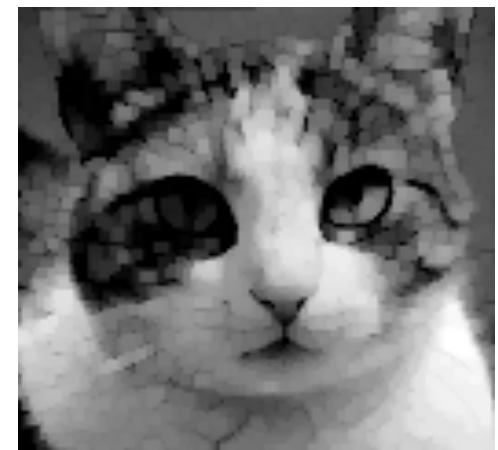


Morphological Filtering in Practice

- Morphological smoothing
 - Opening (i.e., min then max)

$$f \circ b = (f \ominus b) \oplus b$$

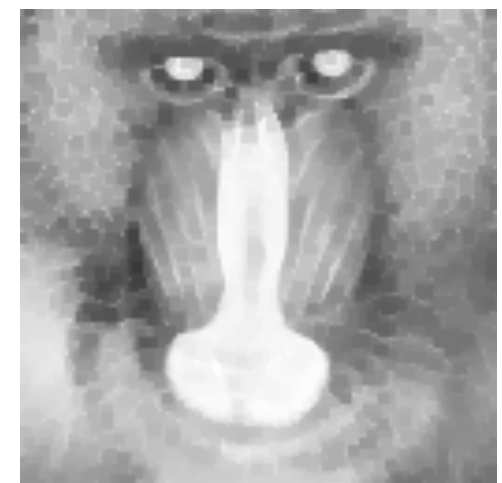
Smoothing by suppression of small bright features



- Closing (i.e., max then min)

$$f \bullet b = (f \oplus b) \ominus b$$

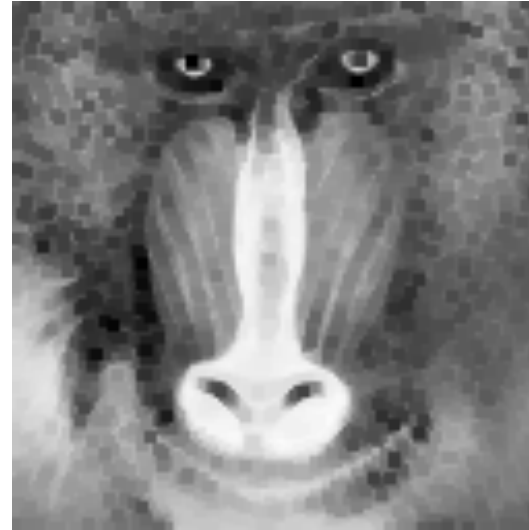
Smoothing by suppression of small dark features



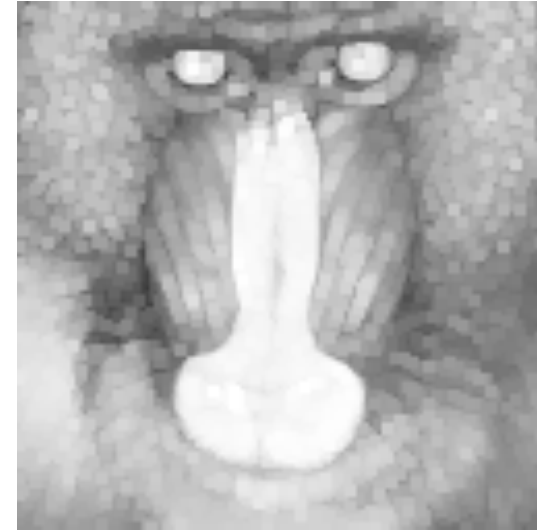
Morphological Filtering in Practice



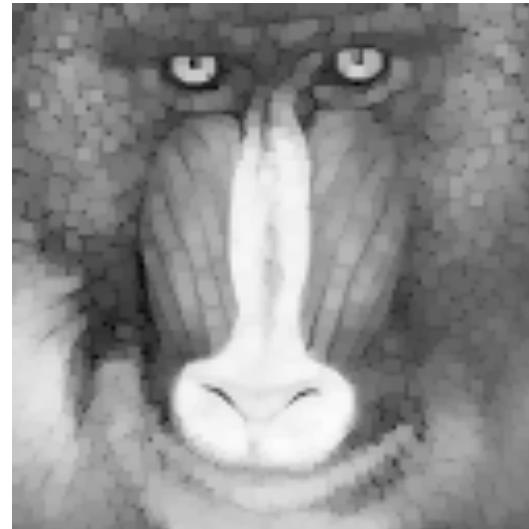
Original (reduced): 128×128



A: 3×3 min



B: 3×3 max



C: 3×3 max of A

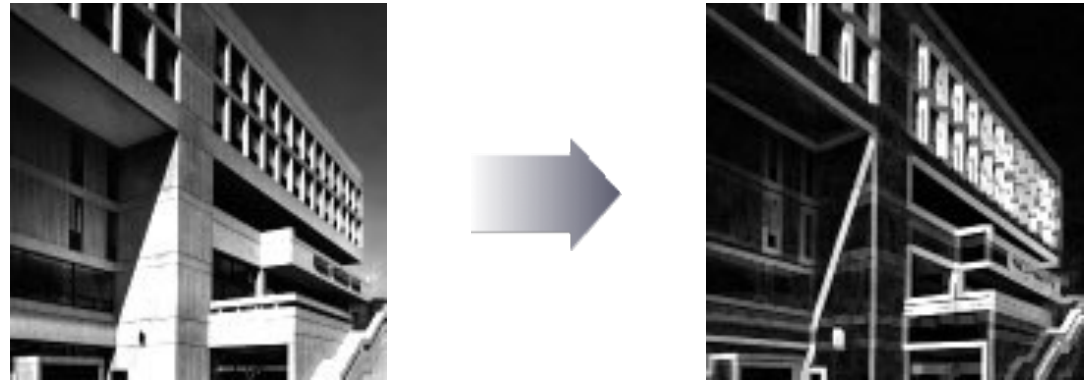


D: 3×3 min of B

Morphological Filtering

- Morphological gradient

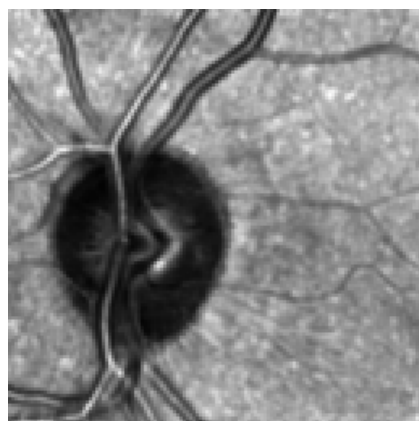
$$g = (f \oplus b) - (f \ominus b)$$



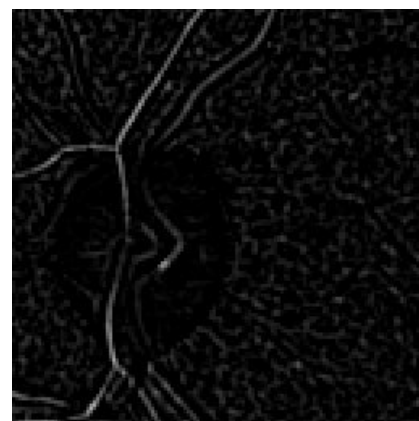
Property: not sensitive to edge direction when using symmetric b

- Top hat

Acts like the Laplacian

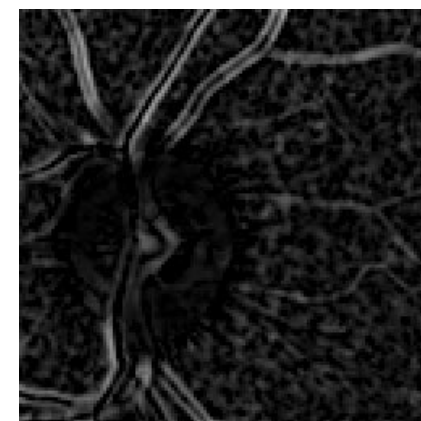


$$g = f - (f \circ b)$$



disk, $r = 1$

$$g = (f \bullet b) - f$$



disk, $r = 3$