# ECE 172A: Introduction to Image Processing Analog Images: Part I

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### **Outline**

- Images as Functions
  - Vector-space formulation
  - Two-Dimensional Systems
- 2D Fourier Transform
  - Properties
  - Dirac Impulse, etc.
- Characterization of LSI Systems
  - Multidimensional Convolution
  - Modeling of Optical Systems
  - Examples of Impulse Responses

### **Images as Functions**

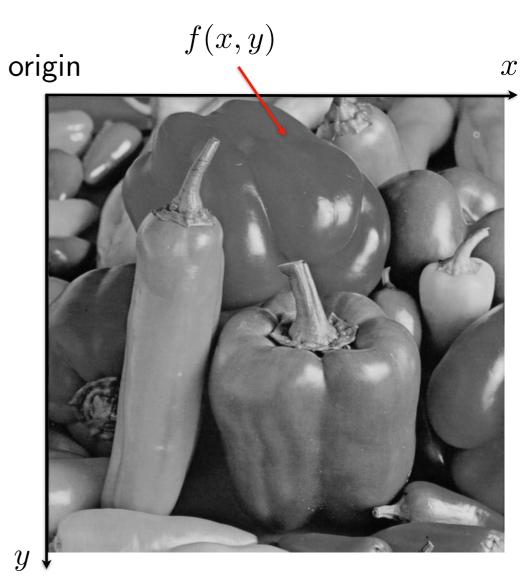
- Analog = Continuously-Defined Image Representation
  - Images are functions of two real variables
- Vector-Space Formulation
  - All images are "points" in a vector space
- Vector Space of Finite-Energy Images
  - Mathematical framework for image representations
- Two-Dimensional Systems
- Linear, Shift-Invariant (LSI) Systems
  - Fundamental tool to "process" images

### **Analog Image Representation**

### **Analog image**

- 2D light intensity function: f(x,y)
- $\bullet$  (x,y) are the spatial coordinates
- The output f(x,y) is the **brightness** (or grayscale level) at (x,y)

 $f: \mathbb{R}^2 \to \mathbb{R}$ 



### **Vector-Space Formulation**

### What is a vector space?

**Definition:** A vector space is a set  $\mathcal{H}$  where, for every  $f, g, h \in \mathcal{H}$  and  $\alpha, \beta \in \mathbb{R}$ , we have that

- Associativity: f + (g + h) = (f + g) + h
- Commutativity: f + g = g + f
- **Identity:** There exists  $0 \in \mathcal{H}$  such that f + 0 = f
- Inverse: There exists  $-f \in \mathcal{H}$  such that f + (-f) = 0
- Compatibility With Scalar Multiplication:  $\alpha(\beta f) = (\alpha \beta) f$
- Multiplication With Scalar Identity 1f = f for  $1 \in \mathbb{R}$
- Distributivity I:  $\alpha(f+g) = \alpha f + \alpha g$
- Distributivity II:  $(\alpha + \beta)f = \alpha f + \beta f$

# **Vector Space of Images**

Do images (functions that map  $\mathbb{R}^2 \to \mathbb{R}$ ) form a vector space?

- Associativity: f + (g + h) = (f + g) + h
- Commutativity: f+g=g+f  $\sqrt{}$  zero(x,y)=0 for all  $(x,y)\in\mathbb{R}^2$
- **Identity:** There exists  $0 \in \mathcal{H}$  such that f + 0 = f
- Inverse: There exists  $-f \in \mathcal{H}$  such that f + (-f) = 0
- Compatibility With Scalar Multiplication:  $\alpha(\beta f) = (\alpha \beta) f$
- Multiplication With Scalar Identity 1f = f for  $1 \in \mathbb{R}$
- Distributivity I:  $\alpha(f+g) = \alpha f + \alpha g$
- Distributivity II:  $(\alpha + \beta)f = \alpha f + \beta f$

Yes, images form a vector space

# **Vector Space of Finite-Energy Images**

**Definition:** The **energy** of an image  $f: \mathbb{R}^2 \to \mathbb{R}$  is

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} |f(x,y)|^2 \, \mathrm{d}x \, \mathrm{d}y$$

**Definition:** The **vector space** of finite-energy images is denoted  $L^2(\mathbb{R}^2)$ 

 $f \in L^2(\mathbb{R}^2)$  if and only if its energy is  $< \infty$ 

$$||f||_{L^2}^2 = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} |f(x,y)|^2 dxdy$$

"squared  $L^2$ -norm of f or energy of f"

measures the "size" of f

**Recall:** Given a vector  $oldsymbol{x} \in \mathbb{R}^N$ 

$$\|\boldsymbol{x}\|_{2}^{2} = \sum_{n=1}^{N} |x_{n}|^{2}$$

# Inner Product of Finite-Energy Images

**Recall:** Given vectors  ${m x},{m y}\in\mathbb{R}^N$ , their inner product is

$$\langle \boldsymbol{x}, \boldsymbol{y} \rangle = \boldsymbol{x}^\mathsf{T} \boldsymbol{y} = \sum_{n=1}^N x_n y_n$$

**Definition:** The inner product of  $f,g\in L^2(\mathbb{R}^2)$  is

conjugate if complex valued

$$\langle f, g \rangle = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) \mathring{g}(x, y) \, \mathrm{d}x \, \mathrm{d}y$$

**Observation:** The norm is **induced by** the inner product

$$||f||_{L^2}^2 = \langle f, f \rangle$$

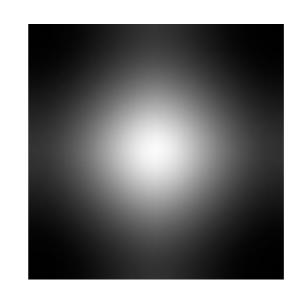
$$L^{2}(\mathbb{R}^{2}) = \{ f(x,y) : ||f||_{L^{2}}^{2} = \langle f, f \rangle < \infty \}$$

### **Examples of Finite-Energy Images**

2D Gaussian

$$g(x,y) = \frac{1}{2\pi} \exp\left(-\frac{x^2 + y^2}{2}\right)$$

$$g \in L^2(\mathbb{R}^2)$$



ullet Finite support  $\Omega\subset\mathbb{R}^2$  and bounded images

$$\begin{cases} f(x,y) = 0, & \text{for all } (x,y) \not\in \Omega \\ |f(x,y)| < C, & \text{for all } (x,y) \in \mathbb{R}^2 \end{cases}$$



$$\Omega = [0, 1] \times [0, 1] = [0, 1]^2$$

**Exercise:** Show that  $f \in L^2(\mathbb{R}^2)$ 

$$||f||_{L^{2}}^{2} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} |f(x,y)|^{2} dxdy$$

$$= \iint_{\Omega} |f(x,y)|^{2} dxdy$$

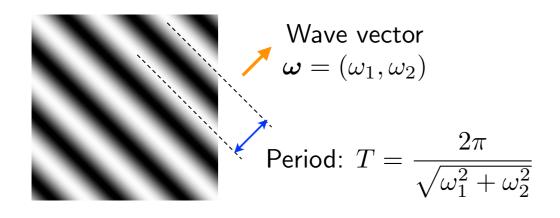
$$< \iint_{\Omega} C^{2} dxdy$$

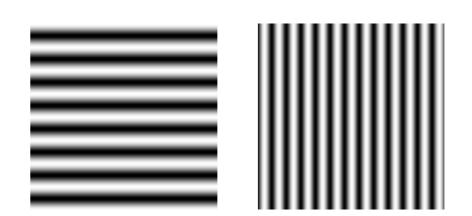
$$= C^{2} \operatorname{vol}(\Omega) < \infty$$

### **Plane Waves**

Sinusoidal gratings

$$s(x,y) = A \cos(\omega_1 x + \omega_2 y + \phi)$$





Does s have finite energy?

No, 
$$s \not\in L^2(\mathbb{R}^2)$$

However, 
$$s(x,y) \cdot w(x,y) \in L^2(\mathbb{R}^2)$$

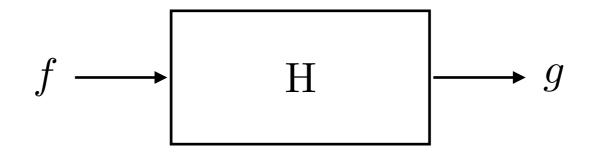
w(x,y) is a finite-support and bounded **window function** 

### **Example:**

$$\begin{cases} w(x,y) = 1, & (x,y) \in [0,1]^2 \\ w(x,y) = 0, & \text{else} \end{cases}$$

### **Two-Dimensional Systems**

Mapping from one image to another



$$H: L^{2}(\mathbb{R}^{2}) \to L^{2}(\mathbb{R}^{2})$$
$$g = H\{f\}$$

The most important systems are linear systems

$$f_{1} \longrightarrow H \longrightarrow g_{1}$$

$$f_{2} \longrightarrow H \longrightarrow g_{2}$$

$$\alpha f_{1} + \beta f_{2} \longrightarrow H \longrightarrow \alpha g_{1} + \beta g_{2}$$

$$H\{\alpha f_1 + \beta f_2\} = \alpha H\{f_1\} + \beta H\{f_2\}$$

# **Linearity Practice**

• (Partial) derivative operators are linear or nonlinear? Linear

$$H_1\{f\} = \frac{\partial f(x,y)}{\partial x}$$
 and  $H_2\{f\} = \frac{\partial f(x,y)}{\partial y}$ 

The following operator is linear or nonlinear? Linear

$$H_3\{f\}(x,y) = f(x^2 + x + 1, y - \sqrt{y})$$

Geometric operators are linear or nonlinear? Linear

$$H_4\{f\}(x,y) = f(G_1(x,y), G_2(x,y))$$

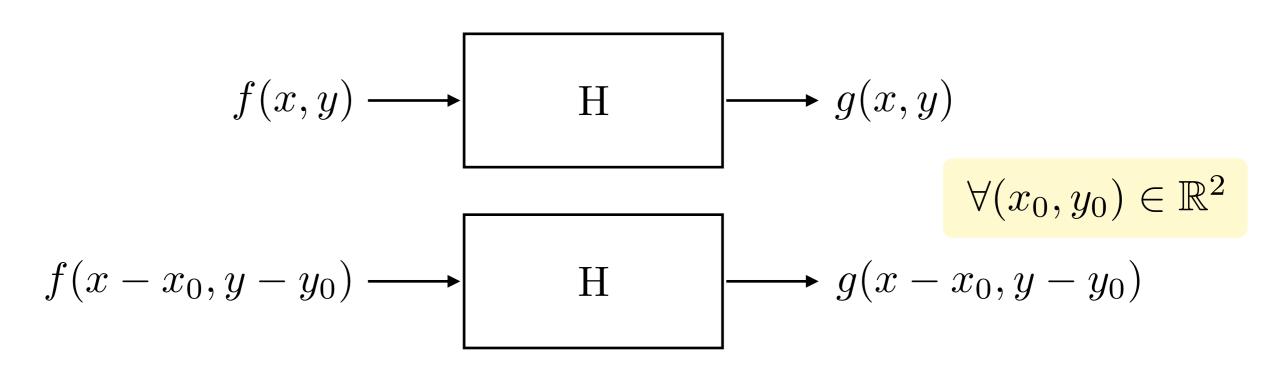
where  $G_1(x,y)$  and  $G_2(x,y)$  are arbitrary (nonlinear) transformations.

The thresholding operator is linear or nonlinear? Nonlinear

$$H_5\{f\}(x,y) = \begin{cases} 1, & |f(x,y)| \ge T_0 \\ 0, & \text{else} \end{cases}$$

# Linear, Shift-Invariant Systems (LSI)

**Definition:** A linear system H is **shift-invariant** if and only if shifted inputs correspond to shifted outputs.



$$H\{f(x-x_0, y-y_0)\} = H\{f\}(x-x_0, y-y_0)$$

LSI systems model most physical imaging devices "impulse response"

LSI = realized by convolution:  $H\{f\}(x,y) = (h*f)(x,y)$ 

### **2D Fourier Transform**

- Definition
- Separability
- Properties
- Dirac impulse
- Dirac related Fourier transforms
- Application: finding the orientation
- Importance of the phase

### 2D Fourier Transform: Definition

- 2D Fourier transform:  $\hat{f}(\omega_1, \omega_2) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-j(\omega_1 x + \omega_2 y)} dx dy$
- Inverse Fourier transform:  $f(x,y) = \frac{1}{(2\pi)^2} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \hat{f}(\omega_1,\omega_2) e^{\mathrm{j}(\omega_1 x + \omega_2 y)} \,\mathrm{d}\omega_1 \,\mathrm{d}\omega_2$

#### **Vector notation:**

Spatial variables:  $\boldsymbol{x} = (x, y) \in \mathbb{R}^2$ 

Frequency variables:  $\boldsymbol{\omega} = (\omega_1, \omega_2) \in \mathbb{R}^2$ 

$$\boldsymbol{\omega}^{\mathsf{T}} \boldsymbol{x} = \omega_1 x + \omega_2 y$$

$$\hat{f}(\boldsymbol{\omega}) = \int_{\mathbb{R}^2} f(\boldsymbol{x}) e^{-j\boldsymbol{\omega}^\mathsf{T} \boldsymbol{x}} d\boldsymbol{x}$$

$$\uparrow \mathcal{F}$$

$$f(\boldsymbol{x}) = \frac{1}{(2\pi)^2} \int_{\mathbb{R}^2} \hat{f}(\boldsymbol{\omega}) e^{j\boldsymbol{\omega}^\mathsf{T} \boldsymbol{x}} d\boldsymbol{\omega}$$

# Plancherel, Parseval, and Finite-Energy

• Fourier analysis on  $L^2(\mathbb{R}^2)$  (Plancherel)

$$f \in L^2(\mathbb{R}^2)$$
 if and only if  $\hat{f} \in L^2(\mathbb{R}^2)$ 

• Parseval's formula for  $f,g\in L^2(\mathbb{R}^2)$ 

$$\langle f, g \rangle = \frac{1}{(2\pi)^2} \langle \hat{f}, \hat{g} \rangle$$

• Plancherel's theorem for  $f \in L^2(\mathbb{R}^2)$ 

$$||f||_{L^2}^2 = \frac{1}{(2\pi)^2} ||\hat{f}||_{L^2}^2$$

What does this mean?

Fourier analysis is well-matched to finite-energy functions

# **Separability**

• Separability of complex exponential:  $e^{-j(\omega_1 x + \omega_2 y)} = e^{-j\omega_1 x} e^{-j\omega_2 y}$ 

2D Fourier transform = sequence of two 1D Fourier transforms

Fourier in x then y or Fourier in y then x

**Exercise:** Show that this is true.

1D Fourier transform in 
$$x$$
: 
$$\int_{-\infty}^{\infty} f(x,y) e^{-j\omega_1 x} dx = \hat{f}_y(\omega_1)$$

1D Fourier transform in 
$$y$$
: 
$$\int_{-\infty}^{\infty} \hat{f}_y(\omega_1) e^{-j\omega_2 y} dy$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x,y) e^{-j\omega_1 x} dx e^{-j\omega_2 y} dy$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-j\omega_1 x} e^{-j\omega_2 y} dx dy = \hat{f}(\omega_1, \omega_2)$$

2D Fourier transform inherits most properties from 1D Fourier transform!

# Separability (cont'd)

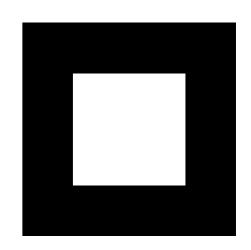
**Definition:** f(x,y) is called separable if  $f(x,y) = f_1(x)f_2(y)$  for some  $f_1(x)$  and  $f_2(y)$ .

**Exercise:** For separable functions, show that  $\hat{f}(\omega_1, \omega_2) = \hat{f}_1(\omega_1)\hat{f}_2(\omega_2)$ .

What is an example of a separable function?

$$f(x,y) = \begin{cases} 1, & \text{if } (x,y) \in [0,1]^2 \\ 0, & \text{else} \end{cases}$$

"box" or "rect" function



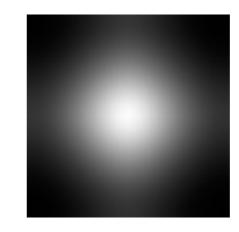
$$f_1(x) = \begin{cases} 1, & \text{if } x \in [0, 1] \\ 0, & \text{else} \end{cases}$$

$$f(x,y) = f_1(x)f_1(y)$$

# Separability (cont'd)

#### 2D Gaussian

$$g(x,y) = \exp\left(-\frac{x^2 + y^2}{2}\right)$$
$$= e^{-x^2/2}e^{-y^2/2}$$



$$\Rightarrow \hat{g}(\omega_1, \omega_2) = \hat{f}(\omega_1)\hat{f}(\omega_2) \quad \text{where } f(x) = e^{-x^2/2}$$

$$\uparrow \mathcal{F}$$

$$\hat{f}(\omega) = \int_{-\infty}^{\infty} f(x)e^{-j\omega x} dx = \sqrt{2\pi}e^{-\omega^2/2}$$

$$\Rightarrow = \sqrt{2\pi}e^{-\omega_1^2/2} \cdot \sqrt{2\pi}e^{-\omega_2^2/2} = 2\pi \exp\left(-\frac{\omega_1^2 + \omega_2^2}{2}\right)$$

Fourier transform of a Gaussian is a Gaussian (just like 1D)

# **Fourier Properties**

Duality:

- Energy-Preservation:
- Shift:
- Modulation:
- Scaling:
- Affine Transformation:
- Differentiation:

$$\hat{f}(\boldsymbol{x}) \stackrel{\mathcal{F}}{\longleftrightarrow} (2\pi)^2 f(-\boldsymbol{\omega})$$

$$f(\boldsymbol{x}) \text{ real} \Leftrightarrow \hat{f}^*(\boldsymbol{\omega}) = \hat{f}(-\boldsymbol{\omega})$$

$$||f||_{L_2}^2 = (2\pi)^{-2} ||\hat{f}||_{L^2}^2$$

$$f(\boldsymbol{x} - \boldsymbol{x}_0) \overset{\mathcal{F}}{\longleftrightarrow} \mathrm{e}^{-\mathrm{j}\boldsymbol{\omega}^\mathsf{T}} \boldsymbol{x}_0 \hat{f}(\boldsymbol{\omega})$$

$$e^{j\boldsymbol{\omega}_0^\mathsf{T} \boldsymbol{x}} f(\boldsymbol{x}) \stackrel{\mathcal{F}}{\longleftrightarrow} \hat{f}(\boldsymbol{\omega} - \boldsymbol{\omega}_0)$$

$$f(\boldsymbol{x}/\alpha) \stackrel{\mathcal{F}}{\longleftrightarrow} |\alpha|^2 \hat{f}(\alpha \boldsymbol{\omega})$$

$$f(\mathbf{A}\boldsymbol{x}) \stackrel{\mathcal{F}}{\longleftrightarrow} |\det \mathbf{A}|^{-1} \hat{f}((\mathbf{A}^{-1})^{\mathsf{T}}\boldsymbol{\omega})$$

$$\frac{\partial^n f(\boldsymbol{x})}{\partial x^n} \overset{\mathcal{F}}{\longleftrightarrow} (\mathrm{j}\omega_1)^n \hat{f}(\boldsymbol{\omega})$$

$$\frac{\partial^n f(\boldsymbol{x})}{\partial y^n} \overset{\mathcal{F}}{\longleftrightarrow} (\mathrm{j}\omega_2)^n \hat{f}(\boldsymbol{\omega})$$

$$\bullet \ \, \text{Moments:} \, \left. \mu_f^{m,n} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x^m y^n f(x,y) \, \mathrm{d}x \, \mathrm{d}y = \left. \mathbf{j}^{m+n} \, \frac{\partial^{m+n} \hat{f}(\pmb{\omega})}{\partial \omega_1^m \partial \omega_2^n} \right|_{\omega_1 = 0, \omega_2 = 0}$$

In particular, 
$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(\boldsymbol{x}) d\boldsymbol{x} = \hat{f}(\boldsymbol{0}) = \hat{f}(0,0)$$

### **Dirac Impulse**

- Recall the 1D Dirac impulse  $\delta(x)$ :  $\langle f, \delta \rangle = \int_{-\infty}^{\infty} f(x) \delta(x) \, \mathrm{d}x = f(0)$
- Properties:

Normalized integral: 
$$\int_{-\infty}^{\infty} \delta(x) dx = 1$$

Fourier transform:  $\delta(x) \stackrel{\mathcal{F}}{\longleftrightarrow} 1$ 

Convolution: 
$$(g * \delta)(x) = \int_{-\infty}^{\infty} \delta(u)g(x - u) du = g(x)$$

**Exercise:** Prove these three properties using the definition.

Normalized integral: f(x) = 1

Fourier transform:  $f(x) = e^{j\omega x}$ 

Convolution: f(u) = g(x - u)

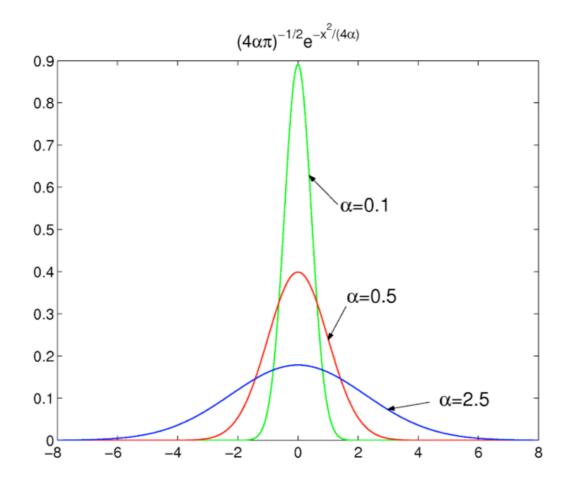
### **Explicit Construction of the Dirac Impulse**

- Consider any window function  $\varphi(x)$  such that  $\int_{-\infty}^{\infty} \varphi(x) \, \mathrm{d}x = 1$
- Observe that  $\int_{-\infty}^{\infty} \frac{1}{|\alpha|} \varphi\left(\frac{x}{\alpha}\right) dx = 1$

"integral-preserving dilation/contraction"

• 
$$\delta(x) = \lim_{\alpha \to 0} \left( \frac{1}{|\alpha|} \varphi\left(\frac{x}{\alpha}\right) \right)$$

e.g.,  $\varphi$  is a Gaussian, rectangle, triangle, etc.



# **2D Dirac Impulse**

• A reasonable definition:  $\langle f, \delta \rangle = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) \delta(x, y) \, \mathrm{d}x = f(0, 0)$ 

What could give us this?

$$\delta(x,y) = \delta(x)\delta(y) \stackrel{\mathcal{F}}{\longleftrightarrow} 1 \cdot 1 = 1$$

The Dirac impulse is **separable**!

**Exercise:** Prove that this is the 2D Dirac impulse.

- Properties:
  - Normalized integral:  $\int_{\mathbb{R}^2} \delta({m x}) \, \mathrm{d}{m x} = 1$

These properties are deduced from the 1D Dirac properties.

- Fourier transform:  $\delta(\boldsymbol{x}) \overset{\mathcal{F}}{\longleftrightarrow} 1$
- Multiplication:  $f(\boldsymbol{x})\delta(\boldsymbol{x}-\boldsymbol{x}_0)=f(\boldsymbol{x}_0)\delta(\boldsymbol{x}-\boldsymbol{x}_0)$
- Sampling:  $\langle f(\boldsymbol{x}), \delta(\boldsymbol{x}-\boldsymbol{x}_0) \rangle = \int_{\mathbb{R}^2} f(\boldsymbol{x}) \delta(\boldsymbol{x}-\boldsymbol{x}_0) \, \mathrm{d}\boldsymbol{x} = f(\boldsymbol{x}_0)$
- Convolution:  $(f * \delta)(\boldsymbol{x}) = f(\boldsymbol{x})$
- Scaling:  $\delta(\boldsymbol{x}/\alpha) = |\alpha|^2 \delta(\boldsymbol{x})$

### **Dirac-Related Fourier Transforms**

Constant

One-dimensional: 
$$1 \stackrel{\mathcal{F}}{\longleftrightarrow} \int_{-\infty}^{\infty} \mathrm{e}^{-\mathrm{j}\omega x} \, \mathrm{d}x = ???$$

$$= \lim_{A \to \infty} \int_{-A}^{A} \mathrm{e}^{-\mathrm{j}\omega x} \, \mathrm{d}x = 2\pi \, \delta(\omega) \qquad \text{(or by duality)}$$

Two-dimensional:  $1 \stackrel{\mathcal{F}}{\longleftrightarrow} (2\pi)^2 \delta(\boldsymbol{\omega}) = (2\pi)^2 \delta(\omega_1, \omega_2)$ 

• Dirac line (or "ideal" line)

$$f(x,y) = \delta(x) \cdot 1 = f_1(x) f_2(y) \xleftarrow{\mathcal{F}} \hat{f}(\omega_1, \omega_2) = \hat{f}_1(\omega_1) \hat{f}_2(\omega_2) = 1 \cdot 2\pi \delta(\omega_2)$$

$$\text{"infinite-amplitude line"}$$

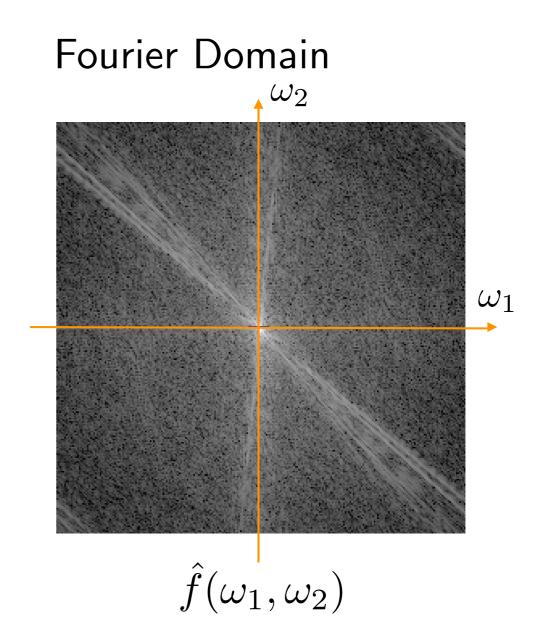
$$x$$

# **Example**

### Spatial Domain



f(x,y)

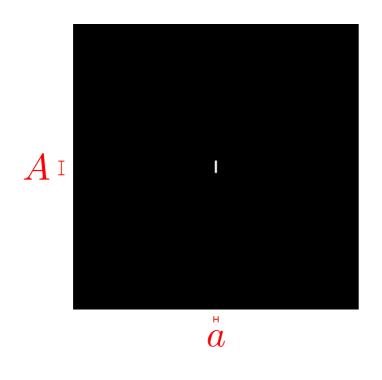


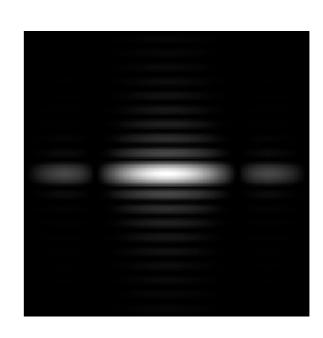
What are these two sets of lines?

### More-Realistic Line Model

### Rectangular shape

$$f(x,y) = \text{rect}(x/a) \operatorname{rect}(y/A) \longleftrightarrow |a| \operatorname{sinc}\left(\frac{a\omega_1}{2\pi}\right) |A| \operatorname{sinc}\left(\frac{A\omega_2}{2\pi}\right)$$





#### **Reminder:**

$$\operatorname{rect}(x) = \begin{cases} 1, & \text{if } x \in [-1/2, 1/2] \\ 0, & \text{else} \end{cases} \qquad \longleftrightarrow \qquad \operatorname{sinc}\left(\frac{\omega}{2\pi}\right) = \frac{\sin(\omega/2)}{\omega/2}$$